

Elastomer Jaw Couplings RINGFEDER[®] GWE 5104

Servo-Insert coupling with clamping hubs and dual slits



	d1;d2	d _{1k} ;d _{2k}									
Size min-max	min-max	min-max	C1	D ₁	D ₃	н	H ₃	I	к	L	L ₃
	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm	mm
14	5 - 16	5 - 16	11	30	30	32,2	13	5	11	35	
19	6 - 20	6 - 20	25	40	40	46	16	12	14,5	66	
24	10 - 32	10 - 32	30	55	55	57	18	10,5	20	78	
28	10 - 38	10 - 38	35	65	65	71	20	11,5	24,5	90	
38	12 - 48	12 - 48	45	80	80	83	24	15,5	30	114	
42	14 - 54	14 - 54	50	95	85	95	26	18	32,5	126	28
48	15 - 60	15 - 60	56	105	95	106	28	21	37	140	32
55	35 - 74	35 - 74	65	120	120	120	30	26	45	160	
65	35 - 80	35 - 80	75	135	135	135	35	28	50	185	
75	30 - 95	30 - 95	85	160	160	160	40	36	60	210	

Transmission of the couplings transmissible torque T can not longer be guaranteed for certain with borings < $d_{min}.$ Types with borings < $d_{min},$ however, can be supplied.

Moment of inertia and weight (mass) are calculated with reference to the largest bore size.

Size	т	H _{es}	n _{max}	J	Gw	D _{G1}	T _{A1}
	Nm		1/min	10 ⁻³ kgm ²	kg	mm	Nm
14	12,5	98 SH A	13000	0,006	0,042	1 x M3	2
19	17	98 SH A	10000	0,036	0,158	1 x M6	11
24	60	98 SH A	7000	0,15	0,304	1 x M6	15
28	160	98 SH A	6000	0,33	0,505	1 x M8	32
38	325	98 SH A	5000	0,96	0,934	1 x M8	38
42	450	98 SH A	4000	4,92	3,8	1 x M10	84
48	525	98 SH A	3600	8,26	4,9	1 x M12	145
55	685	98 SH A	3150	19,15	10,2	1 x M12	145
65	940	98 SH A	2800	30,72	13,7	1 x M12	145
75	1920	98 SH A	2350	66,68	21,34	1 x M16	295

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EN Tech Paper

Transmissible torque T [Nm]

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Size	Ø5	Ø6	Ø8	Ø10	Ø12	Ø14	Ø16	Ø20	Ø25	Ø30	Ø35	Ø40	Ø45	Ø50	Ø55	Ø60	Ø65	Ø70	Ø80	Ø90	Ø95
											Nm										
14	4,8	6,0	7,7	9,4	11	12,5	12,5														
19		16	17	17	17	17	17	17													
24				37	43	50	56	60	60	60											
28				61	72	83	94	114	138	160	160										
38					87	100	113	138	168	197	225	251	277								
42						174	197	242	296	348	398	450	450								
48							276	343	424	502	525	525	525	525	525						
55											630	685	685	685	685	685	685	685			
65											634	714	791	866	940	940	940	940	940		
75											998	1125	1250	1370	1489	1604	1718	1830	1920	1920	1920

Explanations

d ₁ ;d _{2min}	= Min. bore diameter d ₁ /d ₂	
d ₁ ;d _{2max}	= Max. bore diameter d1/d2	
d _{1k} ;d _{2kmin}	 Min. bore diameter d₁/d₂ with keyway acc. to DIN 6885-1 	
d _{1k} ;d _{2kmax}	 Max. bore diameter d₁/d₂ with keyway acc. to DIN 6885-1 	
C ₁	 Guided length in hub bore 	
D ₁	= Outer diameter	

- **D**₃ = Outer diameter hub
- H = Clearance diameter
- H_3 = Length of damping module
 - Distance between center screw hole and hub end
- K = Distance shaft axis clamping screw axis
 - = Total length
- L₃ = Length

Т

L

- \mathbf{T} = Transmissible torque at given T_A
- Hes = Hardness of the elastomeric spider
- **n**max = Max. rotation speed
 - = Total moment of inertia
- Gw = Weight

J

- D_{G1} = Thread
- T_{A1} = Tightened torque of clamping screw D_{G1}

Technical Information
 Hubs up to size 48 made of aluminum, from size 55 made

of steel

Ordering example

Series Size	Bore diameter d ₁	Bore diameter d ₂	Spider hardness (optional) ¹⁾	Spider bore d _{bz} (optional) ¹⁾	Further details	
GWE 5104-42	40	41	64 SH D	42	*	

¹⁾ If a different spider hardness is selected, the detailed technical data for the sprockets must be observed.

See chapter "Elastomer Jaw Couplings RINGFEDER® GWE Technical description" in Product Paper & Tech Paper "RINGFEDER® Elastomer Jaw Couplings"

* Keyway

Further information on

RINGFEDER® GWE 5104

on www.ringfeder.com

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